

**WHAT IS CLAIMED IS:**

1. A method of correcting the refractive error in a cornea of an eye, comprising  
separating a layer of the cornea to form first and second internal surfaces, said  
first surface facing in a posterior direction and said second surface facing in an  
anterior direction, and  
ablating an intracorneal lens, and  
controlling a robot to insert an intracorneal blank proximate to at least one of  
said first and second internal surfaces.
2. A method according to claim 1, wherein  
the separating step includes separating said layer from a remaining portion of  
the cornea at first and second surfaces to form a flap.
3. A method according to claim 2, further comprising the steps of  
moving said flap to expose said second surface.
4. A method according to claim 3, wherein  
said inserting step includes placing said ablated intracorneal blank on said  
second surface.
5. A method according to claim 1, wherein  
said intracorneal blank has a central axis and a centering mark at said central  
axis, and  
said inserting step includes aligning said centering mark of said intracorneal  
blank with the main optical axis of the eye.
6. A method according to claim 5, further comprising the step of  
marking the second surface of the cornea at the main optical axis of the eye.
7. A method according to claim 2, further comprising the step of

smoothing the flap with a compression device.

8. A method according to claim 1, further comprising the step of positioning a therapeutic contact on the external surface of the eye.
9. A method of correcting the refractive error in a cornea of an eye, comprising controlling a first automated device to aim an ultrashort pulse laser at the cornea of the eye,  
firing the ultrashort pulse laser at the cornea of the eye, forming a flap thereon, moving the flap to expose first and second internal corneal surfaces, controlling a second automated device positioning an intracorneal lens on the second internal corneal surface,  
aiming an excimer laser at the intracorneal implant using a third automated device,  
firing the excimer at the intracorneal implant, ablating a portion thereof, replacing the flap over the intracorneal lens, compressing the exterior surface of the cornea, and applying a contact to the exterior surface of the eye to protect the flap.
10. A method according to claim 9, wherein the steps of aiming and firing an ultrashort pulse laser include aiming and firing an ultrashort pulse laser selected from the group consisting of a femtosecond laser, a picosecond laser and an attosecond laser.
11. A method according to claim 10, wherein the placing step includes placing the intracorneal implant on the second internal corneal surface using a plunger.
12. A method according to claim 9, wherein

09082079-101001

the placing step includes placing the intracorneal lens on the second internal corneal surface using a dispensing device coupled to said second automated device.

13. A method according to claim 9, further includes the step of  
marking the second internal corneal surface at the main optical axis of the eye.

14. A method according to claim 13, wherein  
said intracorneal lens has a mark at a central axis thereof, and  
said positioning step includes aligning said intracorneal lens with the mark on  
the second internal corneal surface at the main optical axis.

15. A system for correcting the refractive error in a cornea of an eye of a patient, the  
cornea having an external surface and the eye having a main optical axis, comprising:  
a first robotic arm adapted to be positioned relative said cornea;  
an ultrashort pulse laser coupled to said first robotic arm and adapted to  
separate a layer of the cornea into first and second internal surfaces;  
a second robotic arm adapted to be positioned relative said cornea;  
a lens dispensing device coupled to said second robotic arm and adapted to  
position a lens on the second internal surface of the cornea;  
a third robotic arm adapted to be positioned relative to said cornea; and  
a second laser coupled to the third robotic arm and adapted to ablate a portion  
of said lens.

16. A system according to claim 15, wherein  
said second internal surface is marked at the main optical axis of the eye.

17. A system according to claim 16, wherein  
said lens has a central axis and said lens is marked at said central axis, and  
when said lens is positioned on the external surface of the eye said mark on said lens  
is aligned with said mark on said external surface of said cornea.

18. A system according to claim 15, wherein  
said lens dispensing device is a plunger adapted to hold at two lenses.
19. A system according to claim 15, wherein  
said ultrashort pulse laser is selected from the group consisting of a femtosecond laser, a picosecond laser and an attosecond laser.
20. A system according to claim 15, wherein  
said second laser is an excimer laser.
21. A system according to claim 15, further comprising  
a device for compressing the exterior surface of the eye.